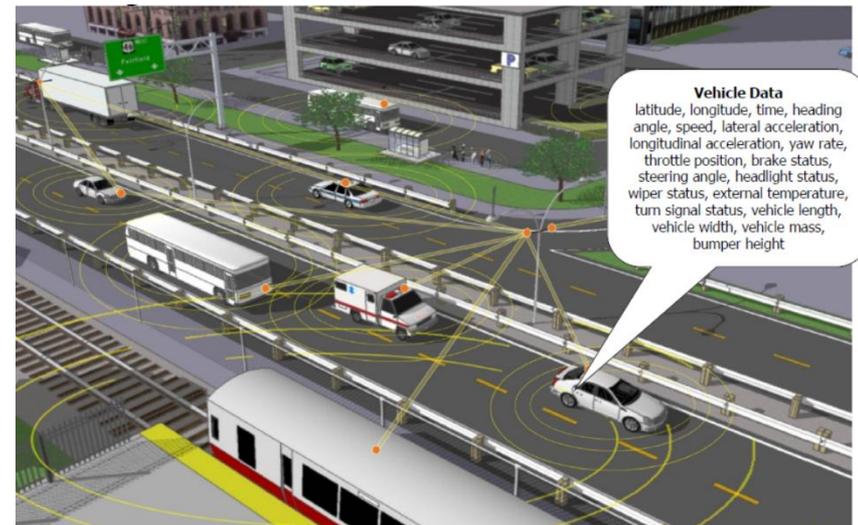


Utilization of Connected Vehicle Data to Support Traffic Management Decisions

Presented by

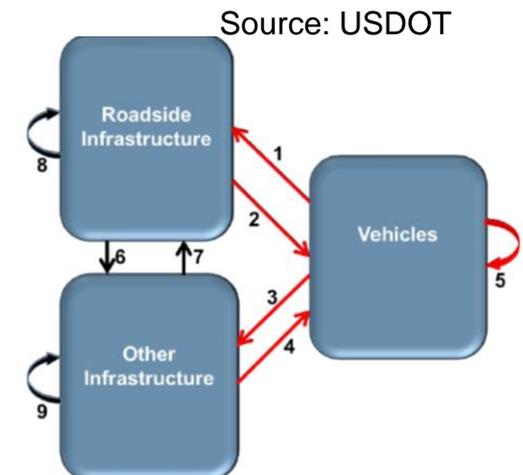
Mohammed Hadi, Ph.D., PE
Florida International University

August, 20th 2015



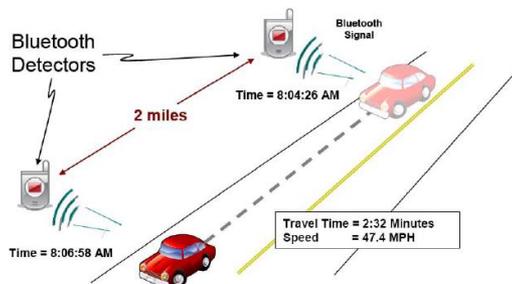
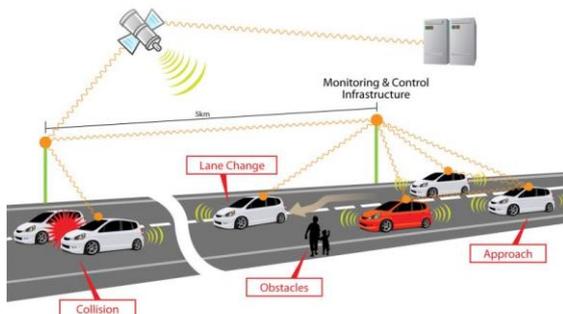
Benefits of Connected Vehicle Data

- Higher details and additional parameters allowing better management
- Better understanding of congestion and influencing factors
- Extended geographic coverage
- Better performance measurements
- Potentially lower data collection costs



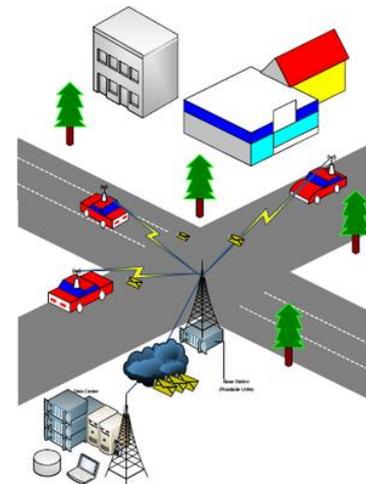
Relevant Statements from AASHTO FootPrint Study

- CV provide opportunities to enhance current capabilities or to reduce ongoing costs of operating and maintaining existing ITS systems.
- Need for assessments and trade-off the use of CV probe data versus traditional ITS detection versus purchasing data
- Connected vehicle technology deployment may complement existing ITS capabilities



Basic Safety Messages

- BSM Part 1 is transmitted at a rate of about 10 times/sec
- BSM Part 2 includes optional data elements transmitted at lower frequencies and when triggered by events
- No vehicle ID → trajectories and O-Ds cannot be generated
- No messages are stored on the OBU
- Can be captured when in the range of RSU or sent through cellular network for V2I applications

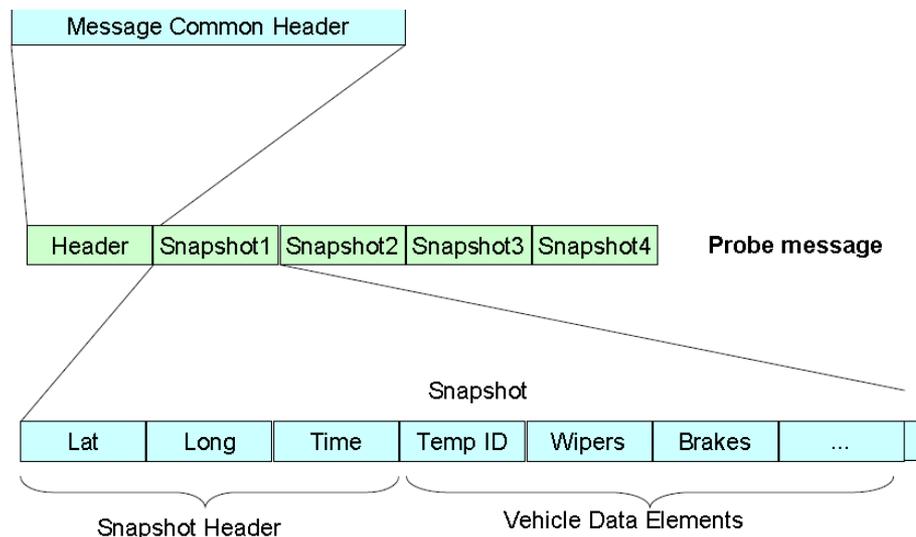


J2735 BSM Message Sets

BSM Message Sets	Messages
BSM Part 1	<ul style="list-style-type: none">• Vehicle position (longitude, latitude, elevation, position accuracy)• Motion (speed, heading, acceleration)• Control (status of brake, traction control, stability control, ABS, Brake Boost, and Auxiliary Brake)• Size (vehicle length, vehicle width).
BSM Part 2 (Optional)	<ul style="list-style-type: none">• Information about events as they occur, such as hard braking, flat tire, or activation of emergency response status, anti-lock brakes, air bag deployment, windshield wipers, etc.• Information about the vehicle's immediate past trajectory; projections for the near-future trajectory• Status of vehicle systems (wiper status, light status, braking status)• Environmental sensor readings• Vehicle physical dimensions• Vehicle identification and description information• Detailed physical information for trucks

Probe Data Management Messages

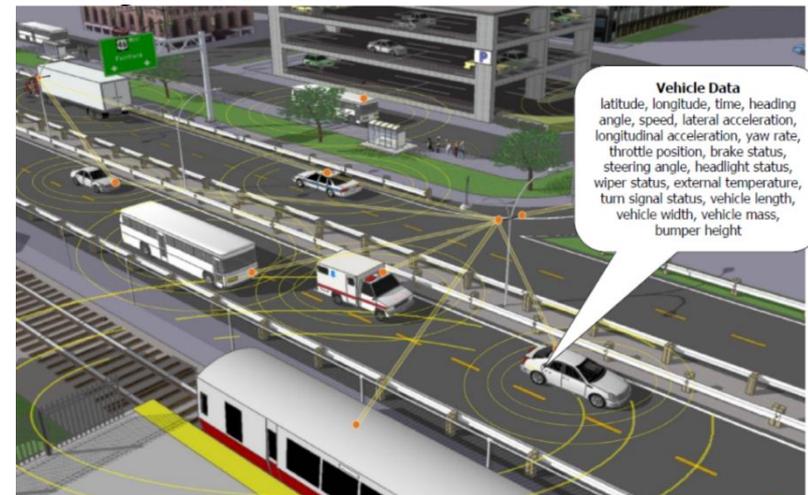
- Snapshots sent periodically
- Protects vehicle anonymity → trajectories and O-D cannot be generated
- Limited number of snapshots saved on OBU and purged after transmission.



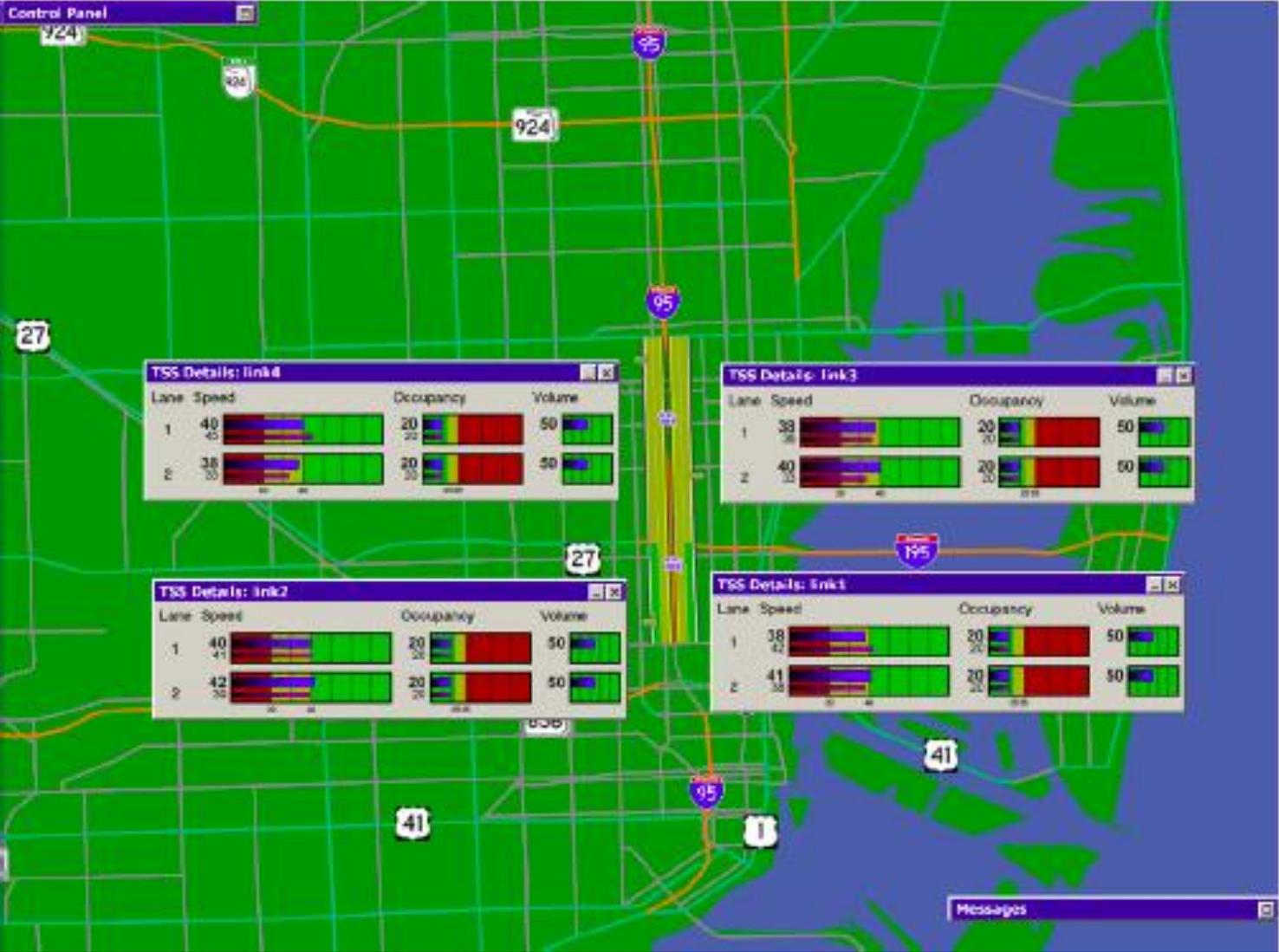
FDOT Research Project

- Examination of the data that can be obtained from connected vehicles
- Identification of the SunGuide TMC processes and modules that will benefit from data
- Examination of the ability of real-world CV deployment to support TMC and potential updates
- Comparing the use of DSRC and cellular technologies

Source: USDOT

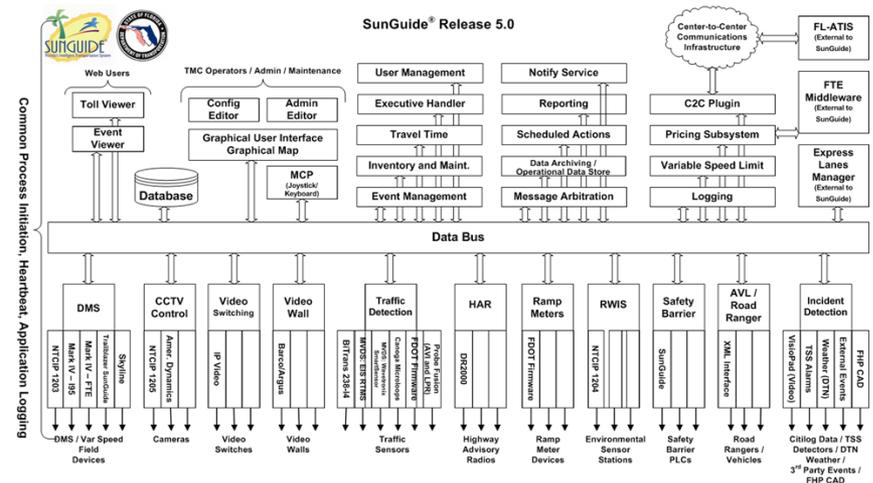


SunGuide Software



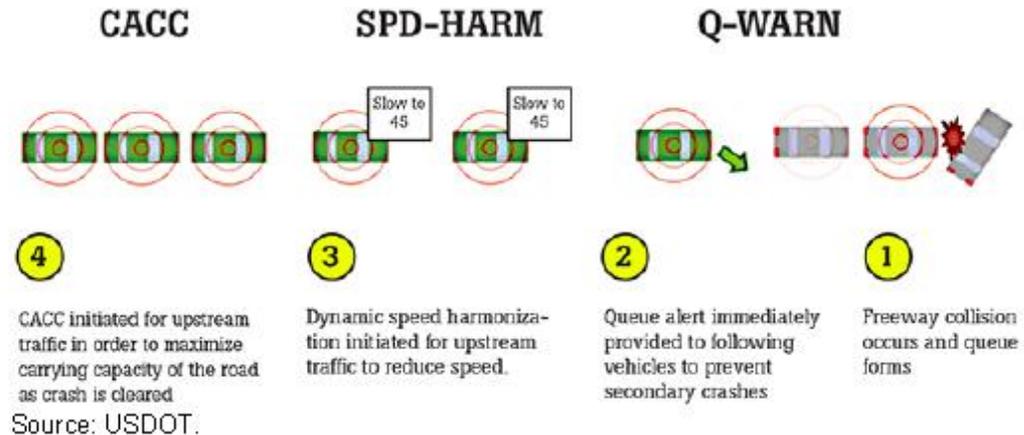
Relation of CV to SunGuide Modules

- Traffic detection and travel time estimation → Real-time performance monitoring
- Data archiving → Performance measurement for planning
- Florida ATIS (FLATIS) → Enable ATIS concepts
- Incident detection → faster with less number of false alarms
- Event Management → Event details, responder details and support/routing, and response/detour plans
- Ramp Meters → Next Generation Ramp Metering
- VSL → Speed Harmonization
- RWIS -> WRM
- Express lanes
- AVL / Road Ranger



Potential Future Applications

- Queue Warning
- Lane Control
- Cooperative adaptive Cruise Control



Data Analytic Tools → ITSDCAP

- Developed for FDOT by FIU to support planning and operations
- Aggregation and processing of data from multiple sources
- Performance measurements and dashboard
- Real-time information sharing
- Prediction of system performance and impacts
- Decision support tools
- Benefit-cost analysis of advanced strategies
- Transportation modeling support → development and calibration

ITSDCAP INTELLIGENT TRANSPORTATION SYSTEM DATA CAPTURE AND PERFORMANCE MANAGEMENT

Account

Main

Real Time Decision Support | Offline Decision Support

Road

1. Route: **Glades Road**

2. Direction: **EB**

3. Start: **St Andrews Blvd**

End: **E University Dr**

Study Period

1. Start Date: **12/16/2013** Start Time (HH:MM): **16 : 00**

2. End Date: **1/2/2014** End Time (HH:MM): **18 : 00**

3. Day of Week: Sun Mon Tue Wed Thu Fri Sat

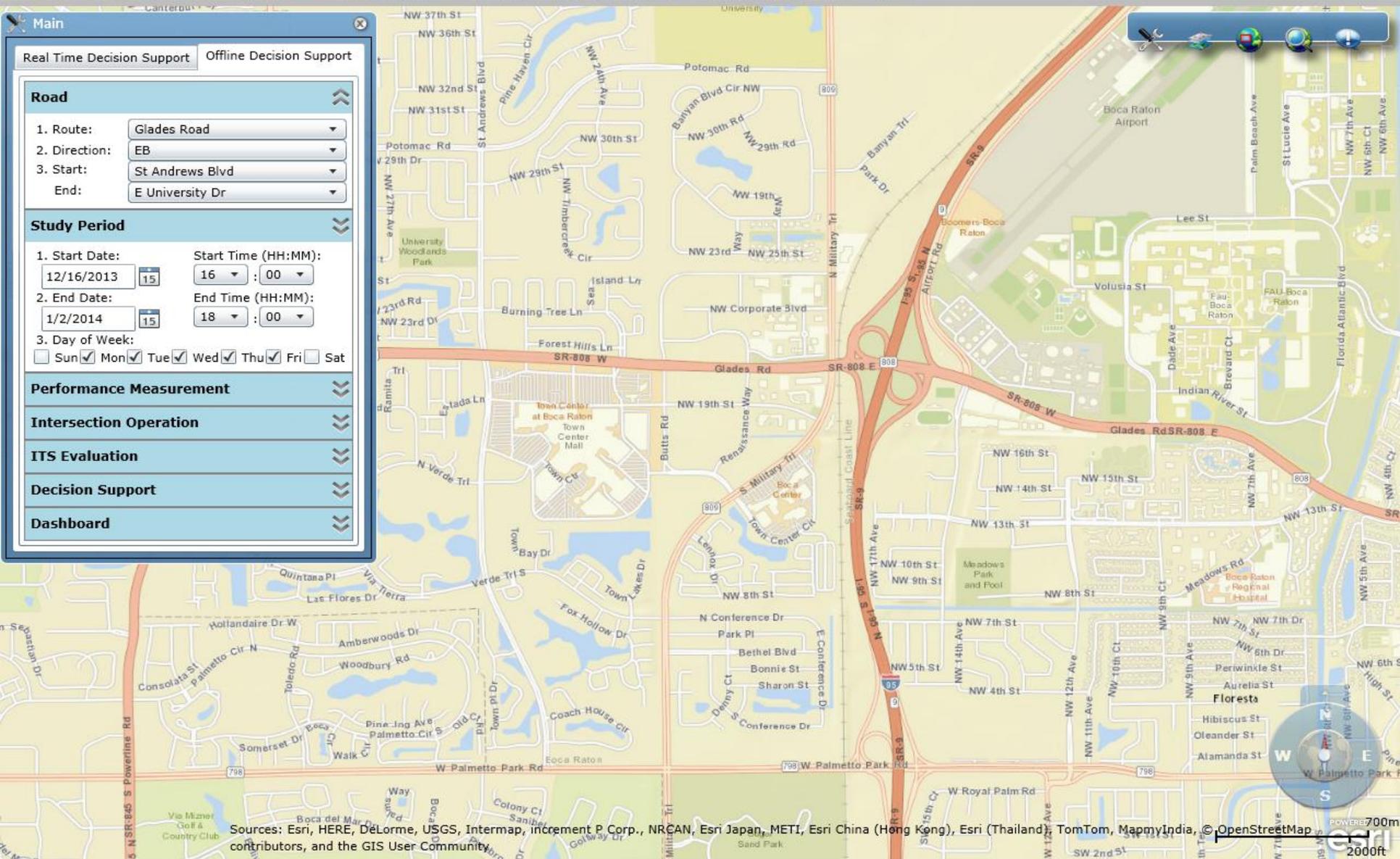
Performance Measurement

Intersection Operation

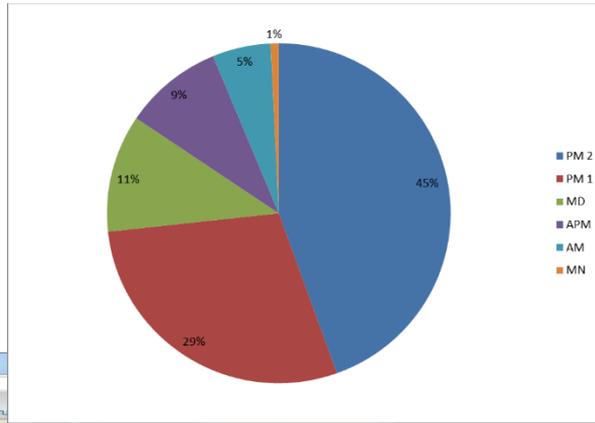
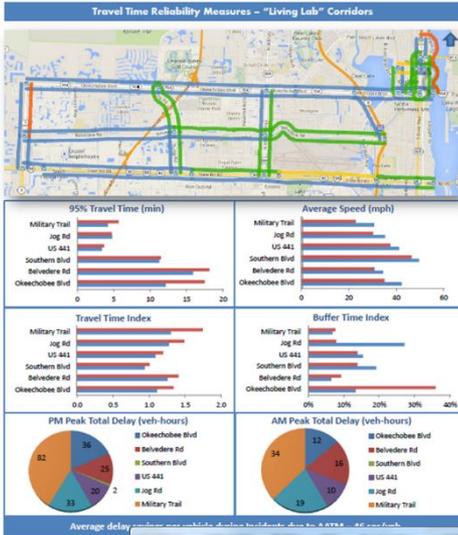
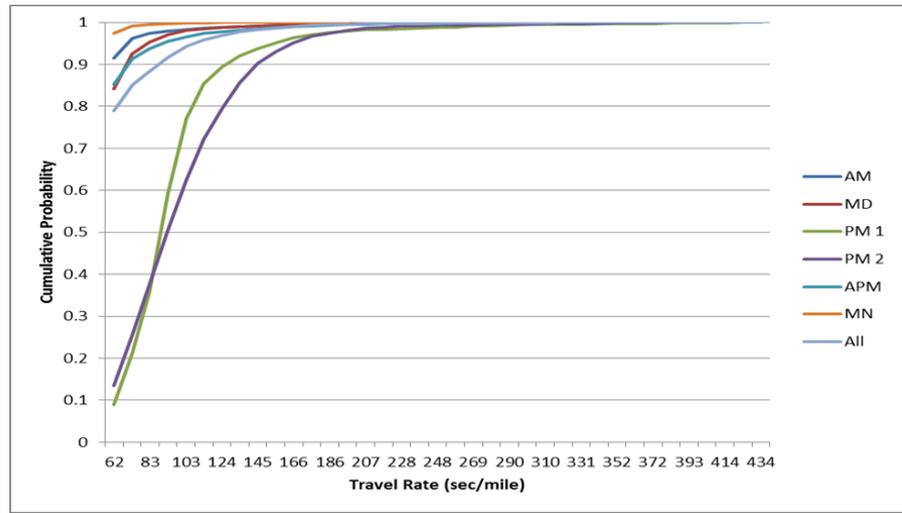
ITS Evaluation

Decision Support

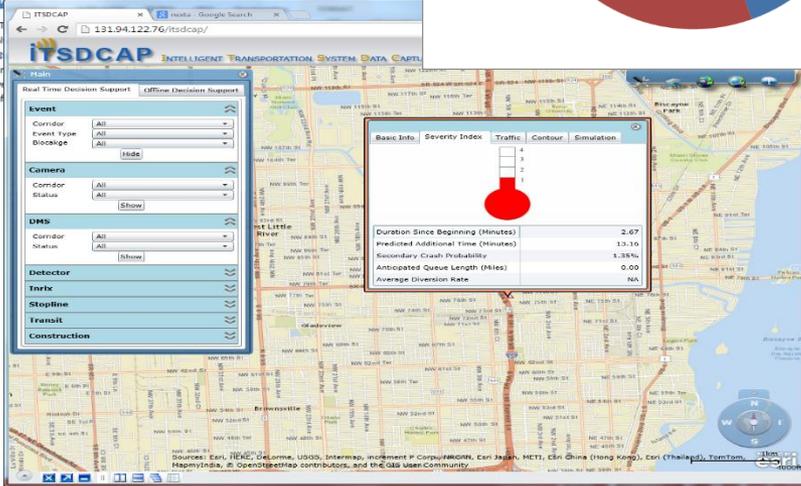
Dashboard



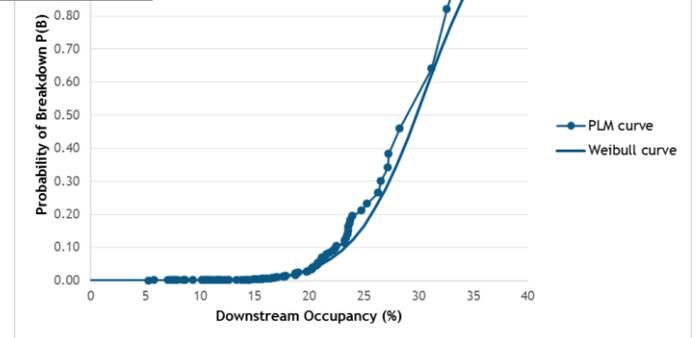
ITSDCAP



Travel Time Index: Travel Time Index conveys how much to multiply expected travel time. Average Buffer Index: Buffer Time Index is much additional time, relative on-time arrival with 95% confidence.



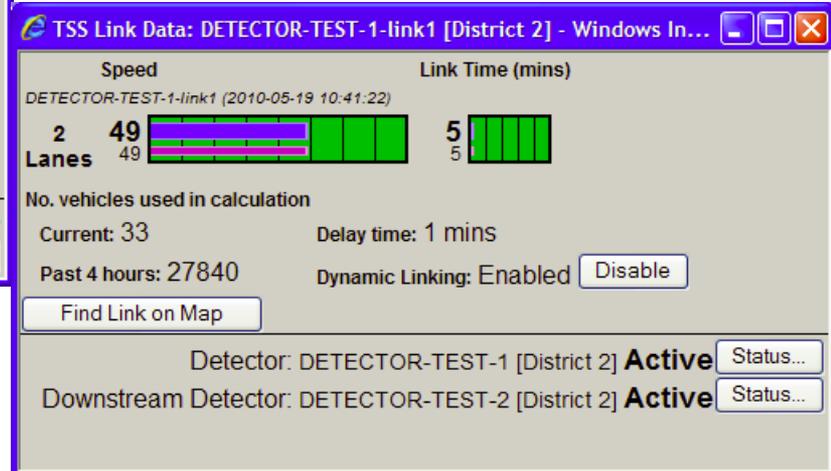
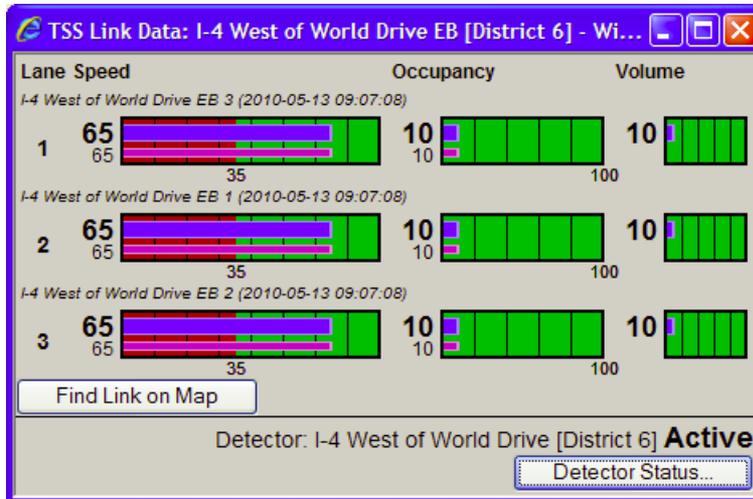
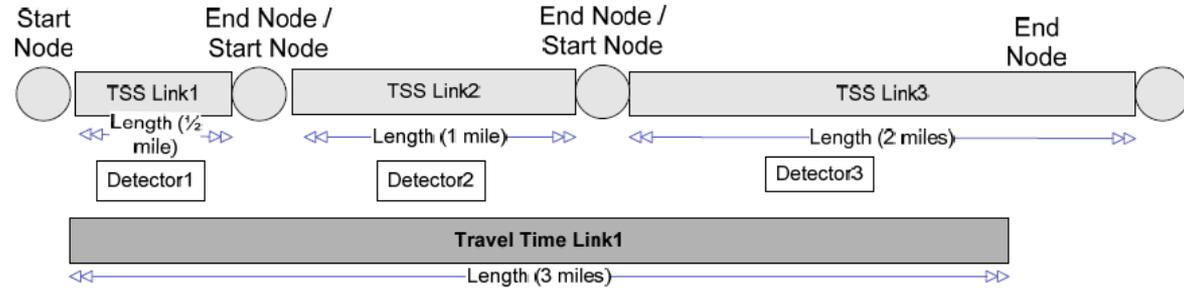
P(B) model for NW 103rd Str. bottleneck



Performance Monitoring for Planning and Operations

- Support estimating measures related to the main goals
 - Mobility
 - Reliability
 - Safety
 - Environmental impacts
- New measures will be possible in these areas
- Better clustering according to conditions and influencing factors
- Arterial and trip-based estimation of performance.

Performance Monitoring in SunGuide

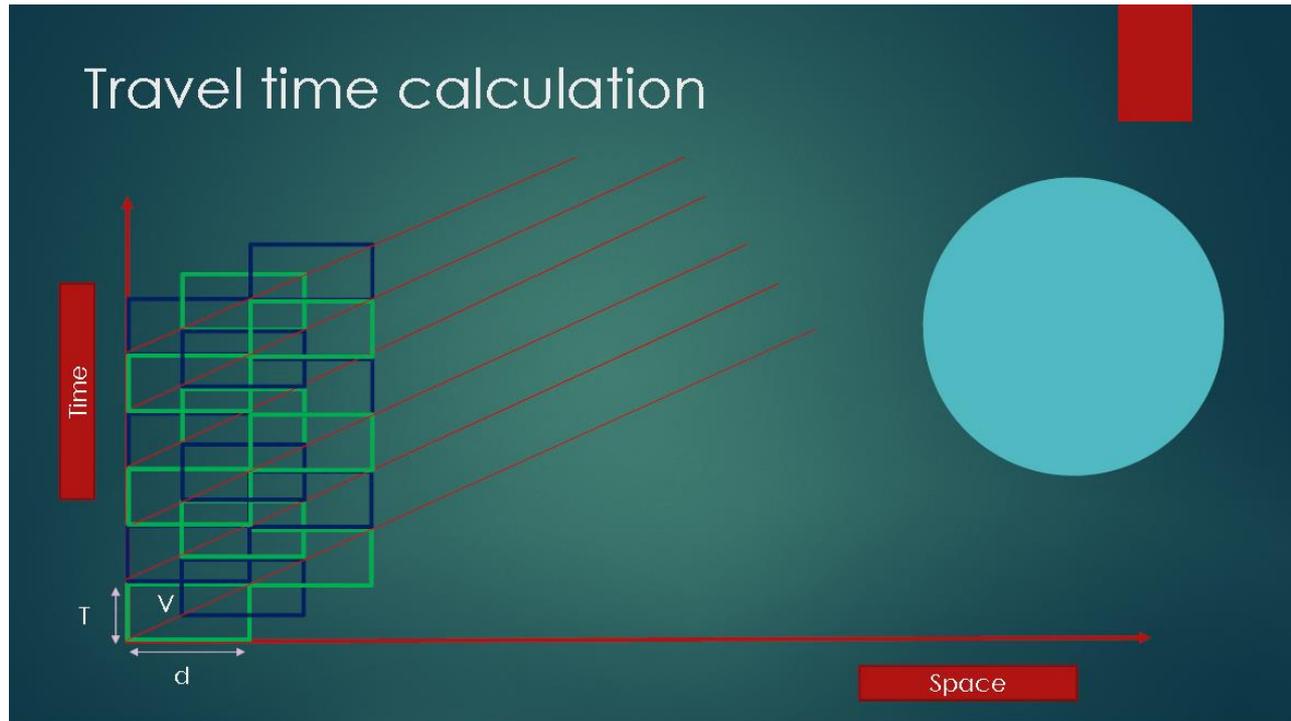


Performance Monitoring based on CV

- Travel times/speeds/delays
- Queue length and back of queue
- Acceleration/ deceleration
- Shockwaves
- Travel time reliability
- Safety performance
- Environmental impacts
- **Volume/throughput/density**

Travel Time Estimation

- Since vehicle trajectories will not be available, virtual trajectory will have to be constructed.

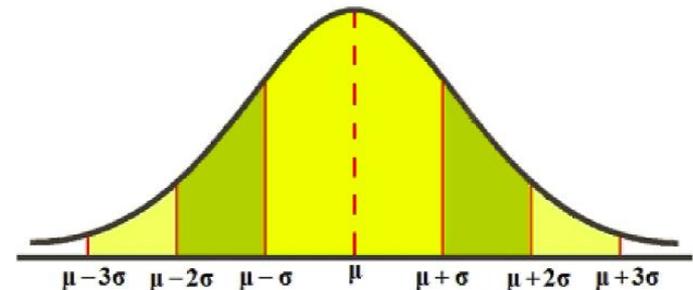


Travel Time Accuracy

Preliminary TT Error Results based on Real-World Trajectories

Current Incident Detection in SunGuide

- Compare current conditions with historical data
- An alarm when speeds on a segment falls below thresholds associated with that segment
- Thresholds are configurable by segment, time of day, and day of week
- Some districts use video analytics to supplement point detection of incidents
- Other sources of detection (FHP, RR, etc.)



Incident Detection based on Detectors

- Past research showed that for most algorithms, the MDT ranges from 0.5-5 minutes (2 minutes typical)
- Cannot detect incident until the queue reaches the upstream detector
 - May take a long time and even may never happen
- Algorithms were also found to produce large numbers of false alarms

Incident Detection using Connected Vehicles

- Several parameters can be used including speed changes, acceleration and deceleration at a specific location, hard brakes, when a vehicle's safety systems have been activated or deployed, or sudden vehicle turns.
- Location can be more accurately specified
- Two methods tested based on acceleration
 - First required only distribution during no incident conditions. Second also requires distributions during incidents
- Use of other parameters are being tested

Preliminary Results

- Preliminary results based on acceleration from simulation is below. Confirmation and further analysis being conducted.

Future Efforts

- Continue testing CV data support of SunGuide based on simulation and existing real-world data
- Examination of the ability of real-world CV deployment to support TMC
- Apply concepts to a real-world deployment of CV